The Convergence and Robustness of Cohort Extensions of Mortality Models

Tom Kennes^{*}

Abstract

The prediction of future of future lifespans of society is known to be very difficult to predict. The most efficient and effective method at the moment of writing is known as the Lee Carter model. However, it has been debated that the intrinsic simplicity of the Lee Carter model and its non-usage of societal trends is not too simple for a complex process such as the average lifespan of currently living people. A strong argument and example can be found in (un)healthy habits of society like smoking and exercise. The simplicity of the Lee Carter model extended with a more abstract form of this structural information gives rise to the cohort extended mortality models. And, although the explanatory power and the underlying rationality might theoretically be valid, in practice it appears that this extension of the model makes the fitting procedure more complex and thus affects the robustness of the model negatively. A possible solution was proposed by Hunt and Villegas (2016) and applied in this paper. Although the theoretical aspect of their solution seems valid, the empirical results show that it is a step in the right direction, but not yet a perfect solution.

1 Introduction

The composition of the population has proved to be an influencing factor for the future of society. Technology over the last 100 years has had a positive effect on the length of people's lives, causing people to beat expectations and grow older. For government policies, as well as insurance and pensions, it is important to accurately predict future mortality rates. As such, forecasting mortality rates in the 21st century has been a field of mathematical computation and speculation. It is however true that opinions vary. Whereas Ray Kurzweil, director of engineering at Google, argued that "By 2029 human will be extending their lives considerably or even indefinitely" (Kurzweil and Grossman, 2005), a survey conducted by a group of Oxford Scientists suggests that humanity faces a 19 % change of extinction over the next century (Sandberg and Bostrom, 2008). As pointed out by Alho (1990) it is often better to forecast based on mortality data

As pointed out by Alho (1990) it is often better to forecast based on mortality data compared to expert opinion. As stated by Lee and Carter (1992) on Alho (1990): "The

^{*}Tom Kennes received a bachelor degree in Econometrics & Operations Research at Maastricht University in 2016, where he currently takes the Research Master in the same field. Contact: t.kennes@student.maastrichtuniversity.nl

use of experts in Actuary hindered rather than helped the forecasts in the past in the sense that statistical time series would have performed better." Starting from the mathematical perspective, the development and the use of mortality models started to become more robust, accurate and omnipresent due to the Lee Carter model. In several papers Haberman and Renshaw (2005; 2006) investigated the possibility of Cohort Extensions and developed what is been called model M and H1. Among others, Cairns et al. (2009) collected a sample of used mortality models and empirically assessed and compared their performance. Its authors note that model M and, in a less degree, H1 provide problems with regard to the fitting procedure and robustness to changes in the data. Cairns et al. (2009) suggest a possible explanation, which is agreed upon, analyzed and solved partially by Hunt and Villegas (2015). The problem is suggested to be caused by flat regions in the log-likelihood function and by adding a non-linearity constraint to the Cohort Effects as well as assuming linearity of the time effect Hunt and Villegas (2015) finds a solution to overcome some of the difficulties in cohort extensions of mortality models.

The paper is organized as followed: first the used notation is introduced, then it starts out by investigating what form the model empirically should have for the best performance. Section 4 then focuses on the development of the Lee Carter model. whereas the fifth section explains the most common used techniques to fit the data to those models. Cohort effects and its extension for the known models are discussed in Section 6 followed by the problems studied encountered while working with those extensions in Section 7. Section 8 and 9 describes the proposed solution and its arguments. Finally, the last section sets out to replicate the results.

2 Notations

 μ_{xt} : central death rate D_{xt} : numbers of death for age x in year t E_{xt} : number of central exposures note that: $\mu_{xt} = E[D_{xt}]/E_{xt}$ α_x : denotes an age-specific constant β_x : denotes the age-specific patterns of change in mortality κ_t : denotes a time-varying index ι_y : denotes the cohort-index

3 Objectivity in Mortality Models

Alho (1990) strongly addresses the methods and their accuracy used by past attempts to forecast, or project, future mortality and fertility rates. Particularly the cohortcomponent method of population forecasting, contributed to P.K Whelpton and collaborators is discussed. This method is developed in a sequence of papers beginning in 1928 (Whelpton (1928); Thompson et al. (1933); Whelpton (1936); Whelpton et al. (1947)). The method starts with an analysis of past mortality data, which are used to form an opinion of the likely future rates at some target year. Intermediate values are then obtained by interpolation. As such a statistical model is set up based on the available data and the future rates of the target year. However, the accuracy of population forecasts did not improve substantially due to these efforts and much of the forecasts made by these forecasts seemed to be way off the actual values later on. The common reaction to the uncertainty has been to call forecasts either "projections" or "illustrative projections". As Alho (1990) stated "as if changing the term would remedy the situation".

Alho (1990) also depicts the formulation of a stochastic version of the mortality model as a solution to the error estimation. This method yields uncertainty intervals, as a byproduct, that hold the probabilities of future mortality rates. Next to that Alho (1990) shows that simple trend extrapolation and the usage of stochastic tools would have been more accurate. Arguing that officials should put less confidence in expert opinion but rely more on statistical techniques.

Much contribution to this school of thinking has been made by the popular Lee and Carter (1992) paper, discussed in later sections, and de León (1990). In the latter, an exploratory data analysis is conducted and several models are empirically tested and discussed for their performance, underlying rationale and complexity. Following the ideas put forward by a.o. Keyfitz (1982), e.g. forecasting methods for mortality rates should be purely statistical with as little complexity as possible, Leon empirically puts forward arguments for multiplicative-additional relational models. Thereby arguing in favor of a structure for the relational model of the form:

$$ln \ \mu(x) = r + \alpha(x) + B\beta(x)$$

In terms of the achieved fit (P-statistic¹ of 95%) this model outperformed other candidates. The result is thus an elegant and simple way of describing a very complex phenomenon which incorporate all of the factors influencing mortality rates in either the age- or the year-component.

4 The Lee Carter Model

Although Lee and Carter (1992) proposes the use of the same model as de León (1990), it is developed independently from Leon. By entirely different routes, they both argue for the same model. Lee and Carter (1992) states the usage of a model that incorporates no knowledge regarding medical, behavioural or social influences on mortality changes but argues for extrapolation procedures and proposes the model:

$$ln(\mu_{xt}) = \alpha_x + \beta_x \kappa_t + \epsilon_{xt}$$

Whereas the error term ϵ_{xt} with mean 0 and variance σ_{ϵ}^2 reflects influences of certain factors that are not captured by the model. Because the data consists only of number of deaths per age per year and number of survivors, one can use the formula for μ_{xt} in Notations to derive the mortality rates for the corresponding years and ages in the sample. The whole left-hand side is thus unknown and has to be estimated. Note that this setting is different compared to the least squares setting with regressors. Furthermore, note that the data is two-dimensional e.g. there is an age (x) component and an period/year (t) component. Finally, this model is concerned with an identification problem. For $1 \le x \le X$ and $1 \le t \le T$ there are 2X + T variables to be estimated whereas the model consists of $X \times T$ equations. As such, there is not one unique solution and the model suffers from an identification problem. The particular solution set is said to be closed with respect to rotation. We can write this as:

$${}^{1}P = \left(1 - \frac{\sum \sum |\epsilon_{ij}|}{\sum \sum |y_{ij} - median(y_{ij})|}\right)$$

$$\alpha_x + \beta_x \kappa_t = \alpha_x + \left(\frac{\beta_x}{c}\right)(c\kappa_t) \ \forall c \neq 0$$

$$\alpha_x + \beta_x \kappa_t = (\alpha_x + d\beta_x) + \beta_x(\kappa_t - d) \ \forall d$$

Whereas c and d are arbitrary constants.

In order to obtain a unique optimal fit, one either has to impose a constraint upon the variables or fix the value of some of the variables. Lee and Carter (1992) chooses to apply:

$$\sum_{x} b_x = 1$$
 and $\sum_{t} k_t = 0$

By choosing these constraints the β_x are normalized and the κ_t sum to zero, implying that:

$$E[ln(\mu_{xt})] = \alpha_x$$

5 Fitting Procedures

In essence, choosing the right model and the right fitting procedure are intertwined. In order to confirm the validity of a model, one has to determine the value of its parameters based on the data. Therefore the fitting procedure is important, nevertheless actuarial literature does not typically favor one consistently over another.

In Lee and Carter (1992) a two-step fitting procedure is proposed. This fitting procedure first sets the main age effects equal to its average over time as:

$$\alpha_x = \frac{1}{T} \sum_{t=1}^T \ln(\mu_{xt})$$

Whereas T denotes the total number of years, or periods, in the sample. Then the other parameters are found by subtracting α_x for each year t of the observed mortality rates as:

$$Z_{xt} = \ln(\mu_{xt}) - \alpha_x$$

As described Good (1969) one can make use of the least square property of the singular value decomposition (hereinafter SVD). From the decomposed matrix one can deduce the values for β_x and κ_t using principal component analysis. The singular value decomposition theorem states that one can rewrite a matrix A with dimension $n \times m$ in terms of an $m \times m$ orthogonal matrix U, a $m \times n$ diagonal matrix Σ with on the diagonal $(\sigma_1, \sigma_2, ..., \sigma_r, 0, 0, ...)$, whereas r < Rank(A) and an $n \times n$ orthogonal matrix V such that:

$$A = U\Sigma V^T$$

Which can be rewritten in outer product form:

$$A = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \dots + \sigma_r \mathbf{u}_r \mathbf{v}_r^T$$

Then the variables in the model are found by:

$$\kappa_t = \sigma_1 \mathbf{v}_1$$
 and $\beta_x = \mathbf{u}_1$

Note that the singular value decomposition is a generalization of the eigendecomposition, or spectral decomposition.

This two-stage approach will generally lead to poorer fits to the available data than a one-stage approach where all the parameters are estimated together. Because the α_x has not been chosen to maximize the goodness of fit. This explicit hierarchy thus biases the estimation of parameter uncertainty as all the uncertainty regarding α_x has been transferred to the uncertainty regarding $\beta_x \kappa_t$. However, this method is often favored due to its computational advantage of being easy to implement, simplicity and general robustness.

It is more difficult to find the variance and error statistics when using the SVD. Moreover, as argued by Alho (2000) the OLS estimation via SVD implicitly assumes that the errors are homoskedastic and normally distributed, which is quite unrealistic. The natural log of the mortality rates are much more variable at older ages compared to the younger ones because of the smaller number of absolute deaths at older ages. Thus as argued by Brouhns et al. (2002) as well as Renshaw and Haberman (2003) it might be favourable to make use of a poisson regression based on heteroscedastic poisson error-structures. As such they implement a likelihood-optimization method based on iteratively improving the fit. This method was described as early as Wilmoth (1993). As argued by Brillinger (1986), the number of Deaths is a count variable, one may assume that the number of deaths follows a Poisson distribution. One considers:

$$D_{xt} \sim \text{Poisson}(E_{xt}\mu_{xt})$$
 with $\mu_{xt} = exp(\alpha_x + \beta_x\kappa_t)$

Whereas the constraints as in Lee and Carter (1992) and the meaning of the parameters are essentially unchanged. These parameters are then iteratively update according to the following updating scheme:

$$\hat{\alpha}_{x}^{(v+1)} = \hat{\alpha}_{x}^{(v)} - \frac{\sum_{t} (D_{xt} - \hat{D}_{xt}^{(v)})}{-\sum_{t} \hat{D}_{xt}^{(v)}} \\ \hat{\kappa}_{t}^{(v+1)} = \hat{\kappa}_{t}^{(v)} - \frac{\sum_{x} (D_{xt} - \hat{D}_{xt}^{(v)})\hat{\beta}_{x}^{(v)}}{-\sum_{x} \hat{D}_{xt}^{v} (\hat{\beta}_{x}^{(v)})^{2}} \\ \hat{\beta}_{x}^{(v+1)} = \hat{\beta}_{x}^{(v)} - \frac{\sum_{t} (D_{xt} - \hat{D}_{xt}^{(v)})\hat{\kappa}_{t}^{(v)}}{-\sum_{t} \hat{D}_{xt}^{v} (\hat{\kappa}_{t}^{(v)})^{2}}$$

Where: $\hat{D}_{xt}^{(v)} = E_{xt} exp(\hat{\alpha}_x^{(v)} + \hat{\beta}_x^{(v)} \hat{\kappa}_t^{(v)})$ With initial values of $\hat{\alpha}_x = 0$, $\hat{\beta}_x = 1$ and $\hat{\kappa}_t = 0$. This updating scheme is called the elementary Ne

This updating scheme is called the elementary Newton method, which was first proposed by Goodman (1979), and is based upon:

$$\hat{\theta}^{(v+1)} = \hat{\theta}^v - \frac{\partial L^{(v)} / \partial \theta}{\partial^2 L^{(v)} / \partial \theta^2}$$

Whereas L denote the likelihood function and θ its parameters. This likelihood-function serves at the backbone of this method as it indicates the likability of a set of parameters to be the actual parameters of the underlying data generating process. It is therefore the function we want to maximize with respect to our parameters e.g. we use to find the optimal fit of the model. In a sense, the fitting process breaks thus, again, down to a maximization procedure. Whereas the SVD minimizes the sum of squared errors, the Poisson regression maximizes the (log)likelihood which can be easily derived from underlying Poisson assumption:

Denote $\lambda = E_{xt} exp(\alpha_x + \beta_x \kappa_t)$. As $D_{xt} \sim \text{Poisson}(\lambda)$, the loglikelihood becomes:

$$f_D(D_{xt},\lambda) = \frac{\lambda^{D_{xt}}e^{-\lambda}}{D_{xt}!}$$

Taking the log:

$$log(f_D(D_{xt},\lambda)) = D_{xt}ln(\lambda) - \lambda - ln(D_{xt}!)$$

Extending this to the log-likelihood-function for the data, separating the constant part $\sum_{xt} ln(D_{xt}!)$ and substituting λ for the equation above this becomes:

$$l(D_{xt},...) = \sum_{xt} \left[D_{xt}(\alpha_x + \beta_x \kappa_t) - E_{xt} exp(\alpha_x + \beta_x \kappa_t) \right] + constant$$

Using this log-likelihood-function and the updating relationships for the parameters one can compute increasingly better fits until a fit is achieved that is perceived as a 'good enough'-fit in terms of log-likelihood improvements. Similarly to 95% being the common confidence interval width indicator, a tolerance level of 10^{-6} increase in the log-likelihood indicates that the fitting procedure has achieved convergence.

It is important to stress that after each update of the parameters the constraints have to be imposed as well. As the parameters merely indicate a space of values with equivalent likelihood and the transformation is an exact one, this does not alter their values in terms of probability but solely helps the method to overcome the identification issues. Also, note that in this procedure the parameters are estimated together termed the "one-stage" estimation. With increasingly larger datasets the algorithm might take considerably longer to compute compared to the SVD, but should provide better fitted values for the parameters in the end. Because α_x is not fixed beforehand, but chosen to be its statistically most likely value.

6 Cohort Extensions

Although the Lee Carter set the stage as an elegant and effective method of forecasting it can be seen as an over-simplistic model as it takes only age and period as parameters. Many studies present evidence for a clear correlation between certain cohorts and mortality rates. Cohorts are based on the notion that certain generations go through specific events that may influence their overall mortality on later ages significantly. Examples are smoking-campaigns or disrupting events such as wars or extreme air- and water-pollution. Those events are not captured in neither age nor period but are collectively explained as the cohort effect. Once again, the model contains a parameter that sort of sums up the influences of a variety of different, maybe even unmeasurable, factors. Hypothetically, it would be a powerful tool to be able to predict the expected lifetime for each cohort. Figure 1 indicates a more graphical representation of cohorts. Depicting the ages vertically and the years horizontally, one can graph the cohorts as diagonal lines in the data grid.

Willets (2004) suggests a number of factors underlying the cohort effect and a number of reasons to believe that cohort effects will have an enduring impact on rates of mortality improvement in future decades. It proposes that certain health benefits including a more healthy diet, health conditions in early life and most notably the overall decline of cigarette consumption and their change over time should be considered as evidence for the existence of cohort effects. Most interestingly, it does so by concerning viewpoints from various scientific fields like epidemiology, sociology and demography data. In a sense, Willets (2004) provides qualitative arguments for cohort extensions of the models. For models which do not incorporate expert knowledge. However, the paper also proposes some quantitative arguments, presented in table 1.

In the interesting paper Tuljapurkar and Boe (1998) criticism has been presented against the inclusion of cohort effects. Based on the evidence presented by de León



Figure 1: Data: Government Actuary's Department (UK). Average annual mortality improvement rate by age and decade for females in the population of England and Wales. Extracted from Willets (2004)

Table 1: Average	annual mortality	improvement	rate $(\%)$ b	y age	and	decade	for	females
in the population	of England and V	Vales						

			Calender year			
Age group	1975	1980	1985	1990	1995	2000
40-44	2.7	3.7	1.0	2.7	1.6	2.3
45-49	2.4	3.0	1.6	2.6	1.3	0.3
50-54	1.0	3.6	2.5	2.0	1.7	1.6
55-59	0.4	1.1	2.4	3.2	1.7	2.5
60-64	0.4	0.5	0.6	2.8	3.2	2.5
65-69	1.2	1.3	0.7	1.4	2.8	3.7
70-74	1.7	1.3	1.0	1.2	1.4	4.0
75-79	1.7	1.9	1.3	1.4	1.3	2.0

Extracted from Willets (2004)

(1990) and Lee and Carter (1992) it concludes that the period factor is more influencing than the cohort effect and that the potential inclusion of the cohort effect does not necessarily lead to better models. As such, the academic community is unsure whether cohort effects should be included. Nevertheless, the cohort extensions do lead to more difficulty in estimating the model and it is interesting to investigate how to incorporated cohort extensions and overcome these problems. Reviewing the quantitative evidence given by Willets (2004) I tend to conclude that those cohort effects could also be explained by the period and age factor as the data presented does not include ages below 40. Furthermore, the data has not been subjected to a formal statistical test and should thus be carefully analyzed.

For scientific reasons it is still interesting to investigate the possibility of incorporating cohort effects into the model. Renshaw and Haberman (2006) investigates the cohort extension. It proposes both model M and model H1, formulated as:

M:
$$ln(\mu_{xt}) = \alpha_x + \beta_x^{(1)}\kappa_t + \beta_x^{(0)}\iota_y$$

H1: $ln(\mu_{xt}) = \alpha_x + \beta_x^{(1)}\kappa_t + \frac{1}{k}\iota_y$

Whereas y = t - x. This identity reflects an important relationship between the parameters of the model. Thus cohort is not linear independent from both period and age. It is destined to be problematic. It is important to note that a simpler model has been used for a longer time outside actuarial literature called the APC - model (Age-Period-Cohort):

APC:
$$ln(\mu_{xt}) = \alpha_x + \frac{1}{k}\kappa_t + \frac{1}{k}\iota_y$$

Because the addition of the new parameters again leads to an identification problem, Renshaw and Haberman (2006) extends the usual constraints by adding:

$$\sum_{x} \beta_{x}^{(0)} = 1$$
 and $\iota_{t_{1}-x_{k}} = 0$

It is important to note that Renshaw and Haberman (2006) uses a two-stage fitting procedure similar to the one used by Lee and Carter (1992) as described in fitting procedures. The α_x is fixed as the mean of $ln(\mu_{xt})$ and subtracted from it, whereas the other parameters are updated as described by James and Segal (1982). The method is comparable to the one described in Brouhns et al. (2002). It also makes use of the Newton Elementary method. Then the deviance compatible with poisson random variables as described in Kaas et al. (2008) is used to assess convergence.

One can simply extend the poisson regression method described in the fitting procedures. It is true that the log-likelihood of other distributions can be used, for example normal, to derive the updating scheme and fit the model. However, for the same reason regarding the error structure given in the fitting procedures, I will stick to the method as stated by Brouhns et al. (2002). Then, a different constraint than the one used in Renshaw and Haberman (2006) is needed:

$$\sum_{y} \iota_{y} = 0$$

This will give:

$$l(D_{xt},...) = \sum_{xt} \left[D_{xt}(\alpha_x + \beta_x^{(1)}\kappa_t + \beta_x^{(0)}\iota_y) - E_{xt}exp(\alpha_x + \beta_x^{(1)}\kappa_t) + \beta_x^{(0)}\iota_y \right] + constant$$

Using the elementary Newton method one obtains the same parameter scheme plus two new ones for the added constraints as:

$$\hat{\iota}_{y}^{(v+1)} = \hat{\iota}_{y}^{(v)} - \frac{\sum_{x,t;t-x=y} (D_{xt} - \hat{D}_{xt})\hat{\beta}_{x}^{(0),(v)}}{-\sum_{x,t;t-x=y} \hat{D}_{xt}(\hat{\beta}_{x}^{(0),(v)})^{2}} \\ \hat{\beta}_{x}^{(0),(v+1)} = \hat{\beta}_{x}^{(0),(v)} - \frac{\sum_{t} (D_{xt} - \hat{D}_{xt})\hat{\iota}_{t-x}^{(v)}}{-\sum_{t} \hat{D}_{xt}(\hat{\iota}_{x-t}^{(v)})^{2}}$$

Renshaw and Haberman (2006) provide an answer to the question regarding the additional structural effects of the cohorts as fundamental aspects of mortality patterns. This is based on an analysis regarding residuals of different models. The residuals, shown in figure 2, indicate that the Lee Carter fails to capture cohort effects as they are incorporated in the calendar-year residual plots under age-cohort modeling. However, the effects are largely removed under model M, representing a significant improvement over the fitted Lee-Carter model. Thus, there is some evidence for the presence of cohort effects, albeit not really statistically convincing. What is interesting though, is the side-note made by Renshaw and Haberman (2006) stating for model M converging is slow when fitting M. The next sections elaborate on this observation.



Figure 2: Females, England and Wales data, residual plots: Lee Carter model (top) and model M (bottom). Extracted from Renshaw and Haberman (2006)

7 Problems in Cohort Extended models

Next to Renshaw and Haberman (2006), other studies observed difficulties arising due to the Cohort Extended Models as well. Cairns et al. (2009) describes a quantitative comparison between various stochastic mortality models based on England and Wales mortality data. Amongst others, these include the Lee Carter model, model M as proposed by Renshaw and Haberman (2006) and the APC-model. The M model is estimated using the one-stage approach, whereas the fitting procedure for APC is slightly altered. Using the model:

$$ln(\mu_{xt}) = \alpha_x + \kappa_t + \iota_y$$

The following constraints are imposed:

$$\sum_t \kappa_t = 0$$
 and $\sum_y \iota_y = 0$

Since the final solution needs one other constraint to be identifiable as we can add:

$$ln(\mu_{xt}) = \left[\alpha_x + \delta(x - \bar{x})\right] + \left[\kappa_t - \delta(t - \bar{t})\right] + \left[\iota_y + \delta\left((t - \bar{t}) - (x - \bar{x})\right)\right]$$

This has thus no impact on the final solution. Note that δ in this case is a tilt parameter indicating the value of the slope. Cairns et al. (2009) proposes to chose δ within the iterative scheme to minimize:

$$S(\delta) = \sum_{x} \left(\alpha_x + \hat{\delta}_x^2 (x - \bar{x}) - \hat{\alpha}_x \right)^2$$

With $\hat{\alpha}_x = \frac{1}{n} \sum_t ln(\mu_{xt})$. Minimizing this equation with respect to δ yields:

$$\delta = -\frac{\sum_x (x-\bar{x})(\alpha_x - \hat{\alpha}_x)}{\sum_x (x-\bar{x})^2}$$

Note that we are actually using the linearity in the mean of the $ln(\mu_{xt})$ as δ can be seen as the ordinary least squares solution of the regressor coefficient. Then the revised parameter estimates become:

 $\tilde{\kappa}_t = \kappa_t - \delta(t - \bar{t})$ $\tilde{\iota}_y = \iota_y + \delta((t - \bar{t}) - (x - \bar{x}))$ $\tilde{\beta}_x = \beta_x + \delta(x - \bar{x})$

The conclusions, regarding model M, drawn by Cairns et al. (2009) are similar to the side-note made by Renshaw and Haberman (2006) in the previous section. Namely, it firmly claims that model M, although standing out as having the best BIC-number and the lowest variance, produces results that lack robustness, as the parameter estimates change very significantly when less data is used. Cairns et al. (2009) states that parameter estimates jump to a qualitatively different solution when less data is used. This leads to, as the authors of Dowd et al. (2010) state, "the forecasts are clearly unstable,... these projections reflect estimates of the cohort state variable that are sometimes very unstable and highly implausible if we move from one sample to the next". As such, the reliability of its forecasts should be questioned. Furthermore, it is suggested that the parameter values in the iterative scheme converge very slowly to their maximum likelihood estimates. Even more so, in some instances, the model seems to breakdown altogether. In such a case, the model does not achieve convergence at all. These results have been confirmed by Lovász (2011) and Currie (2016). It is thought that the convergence problem is due to some sort of identifiability issue in the likelihood function. This is further elaborated in the next section.

Model APC scores better. Next to its relative ease of implementation compared to model M, it does not lack robustness and is does not encounter convergence problems in the fitting procedure, according to Cairns et al. (2009).

8 Hunt and Villegas (2015): a Possible Solution

In summary, the estimation of the parameters of model M is not robust with respect to small changes in the data and the fitting procedure results in a slow convergence and sometimes even no convergence at all. This is problematic as produced forecasts by the model lack credibility. As expressed by Cairns et al. (2009) the model might be dealing with either an approximate or an exact identification issue. That is, approximately (or exactly) flat regions in the loglikelihoodfunction that makes the convergence slow (or unsuccessful). In Hunt and Villegas (2015) the authors state that they have found the identification issue in question. They observed the robustness and convergence issues of model M, using data on England and Wales Males between 1961-2007. They observed that model M and H1 could show large changes in the patterns of fitted parameters for relative small changes in the fit to data, as depicted in the graphs in figure 3.



Figure 3: Parameters for Model M for different start years using the one-stage approach.

They noted that the changes were of the following form:

- a tilting in the cohort parameters ι_y around the midpoint of the range.
- a tilting in the period parameters κ_t around the midpoint of the range.
- some tilting of the static age function α_x with it becoming considerably less smooth as the tilt in ι_y increases in model M
- a lack of robustness in the age function $\beta_x^{(1)}$ with it picking up some of the features of $\beta_x^{(0)}$ in some cases.
- the age function $\beta_x^{(0)}$ remaining largely unchanged.

Thus, any solution should take this in mind. Next, I will first derive the solution and its impact on the log-likelihood, then I will argue why this is a solution. Keeping the above observations and the already applied constraints in mind, Hunt and Villegas (2015) comes up with an additional constraint based on both the assumption of linearity of κ_t and the assumption that the cohort effect is random. Rewrite:

$$\kappa_t = K(t - \bar{t}) + \delta_t$$

With $\bar{t} = 0.5(t_1 + t_n)$. Because in most datasets κ_t tends to be linear, we expect δ_t to be small. However, we may always rewrite model M as:

$$log(\mu_{xt}) = \alpha_x + \beta_x^{(1)} (K(t - \bar{t}) + \delta_t) + \beta_x^{(0)} \iota_{t-x}$$

Note that, because of the identification issue, we can rewrite the parameters as:

$$\tilde{\alpha}_x, \tilde{\beta}_x^{(0)}, \tilde{\kappa}_t, \tilde{\beta}_x^{(0)}, \tilde{\iota}_y = \left[\alpha_x + e\beta_x^{(0)}(x - \bar{x}), \frac{K}{K - e}\beta_x^{(1)} - \frac{e}{K - e}\beta_x^{(0)}, \frac{K - e}{K}\kappa_t, \beta_x^{(0)}, \iota_y + e(y - \bar{y})\right]$$

Whereas \bar{y} and \bar{x} are similar to \bar{t} and:

$$K = \frac{\sum_{t} (t-\bar{t})\hat{\kappa}_{t}}{\sum_{t} (t-\bar{t})^{2}}$$
$$e = -\frac{\sum_{y} (y-\bar{y})\hat{\iota}_{y}}{\sum_{y} (y-\bar{y})^{2}}$$

Thus, K is found by regressing κ_t on $t - \bar{t}$ uch that $\kappa_t = K(t - \bar{t}) + \delta_t$, $\delta_t \sim N(0, \sigma_K^2)$, and e, s is found by regressing ι_y on $y - \bar{y}$ such that $\iota_y = e(y - \bar{y}) + \xi_y$, $\xi_y \sim N(0, \sigma_i^2)$

By simply substituting the formula for
$$\kappa_t$$
 in the equation, it can be shown that:

$$\mu_{xt} = \alpha_x + e\beta_x^{(0)}(x - \bar{x}) + \left(\frac{K}{K-e}\beta_x^{(1)} - \frac{e}{e-K}\beta_x^{(0)}\right)\frac{K-e}{K}\kappa_t + \beta_x^{(0)}(\iota_y + e(y - \bar{y}))$$

$$= \alpha_x + \beta_x^{(1)}\kappa_t + \beta_x^{(0)}\iota_y + \beta_x^{(0)}\left(e(x - \bar{x}) - \frac{e}{k}\beta_x^{(0)}\kappa_t + e(y - \bar{y})\right)$$

$$= \alpha_x + \beta_x^{(1)}\kappa_t + \beta_x^{(0)}\iota_y + \beta_x^{(0)}e\left((x - \bar{x}) - (t - \bar{t}) - \frac{\delta_t}{K} + (y - \bar{y})\right)$$

$$= \alpha_x + \beta_x^{(1)}\kappa_t + \beta_x^{(0)}\iota_y - \frac{e}{K}\beta_x^{(0)}\delta_t$$

Thus the transformation is not an exact one but an approximate as the transformed fitted mortality rates relate the to original fitted ones by:

$$log(\tilde{\mu_{xt}}) = log(\mu_{xt}) - \epsilon_{xt}$$
 Whereas $\epsilon_{xt} = \frac{e}{K} \beta_x^{(0)} \delta_x^{(0)}$

Taylor expanding the the poisson loglikelihood, given by:

$$L(D_{xt}, \hat{D}_{xt}) = \sum_{x} \sum_{t} w_{xt} \left[D_{xt} log(\hat{D}_{xt}) - \hat{D}_{xt} - log(D_{xt}!) \right]$$

for the death counts using the transformed mortality rates \tilde{D}_{xt} around the original fitted death counts \hat{D}_{xt} gives:

$$L(D_{xt}, \tilde{D}_{xt}) = L(D_{xt}, \hat{D}_{xt}) - \sum_{x} \sum_{t} w_{xt} (D_{xt} - \hat{D}_{xt}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{x} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt}^{2} + O(\eta^{*2}) \eta_{xt} - \frac{1}{2} \sum_{t} w_{xt} \hat{D}_{xt} \eta_{xt} - \frac{1}{$$

where $\eta^* = max|\eta_{xt}|$ Note that we for small values of δ_t or small values of e we get approximately unchanged fitted values. This means that for this method to be useful either κ_t should be very linear or e should be very small. Otherwise, the transformation may change the parameters significantly and thus will decrease the fit significantly as well. Because most data sets will have approximately linear κ_t , the set of constraints can be extended by adding the constraint that e should be zero, or, because e can be obtained from the regression as discussed earlier:

$$\sum_{y} \left(y - \bar{y} \right) \iota_{y} = 0$$

Although Hunt and Villegas (2015) foremost described e as the tilt of the parameters, it has another attribute, namely for e = 0 we get that $\iota_y = \xi_y$ and thus that ι_y is random, which is in line with Renshaw and Haberman (2006). Thus, over time the changes in mortality rates should be controlled by the period functions.

In later sections, the authors of Hunt and Villegas (2015) describe evidence for this additional constraint. Empirically, they show that the convergence rate is higher for English and Wales Males data for ages 0 - 89 when the constraint is used. By setting the tolerance of convergence stricter, e.g. the difference between sequentially obtained loglikelihoods during the iteration should be smaller to stop the iteration, they obtained the following results table 2 and table 3.

The convergence and Robustness of Cohort Extensions..... 47

		0 11		
Tolerance	Model M		Model H1	
	Log	Computing	Log	Computing
	likelihood	time(s)	likelihood	$\operatorname{time}(s)$
10^{-3}	-22,006	22	-22,410	13
10^{-4}	-21,991	115	-22,400	67
10^{-5}	-21,986	437	-22,396	234
10^{-6}	-21,984	1393	-22,395	643
10^{-7}	-21,984	2377	-22,395	1228

Table 2: Poisson log-likelihood and computing time in seconds for Models M and H1 for different tolerance levels in the one-stage approach

Table 3: Poisson log-likelihood and computing time in seconds for Models M and H1 for different tolerance levels in the one-stage approach with the approximate identifiability constrain

Tolerance	Model M		Model H1	
	Log	Computing	Log	Computing
	likelihood	$\operatorname{time}(s)$	likelihood	time(s)
10^{-3}	-22,007	10	-22,408	5
10^{-4}	-21,005	20	-22,407	8
10^{-5}	-21,005	31	-22,407	13
10^{-6}	-21,005	43	-22,407	17
10^{-7}	-21,005	53	-22,407	21

Thus, the computing time has been speeded up, whereas the fit is just slightly worse. However, although the convergence problem seems to be solved for both Models M and H1, this cannot be said about the robustness issue. Model M is still quite unstable with regard to changes of in the data in both the age and period dimension. Model H1, being more simplistic, was already quite robust, and this has not changed by the added constraint as well.

An important note I like to add is that one cannot blindly included the constraint. In essence, one is trying to fix certain characteristics of the global structure of the data, which differs between datasets. For the Hunt and Villegas constraint, it is shown by the authors of the paper themselves, the results are not universal for all datasets.

9 Hunt and Villegas (2015): Tests on Other Datasets

In other studies, similar problems with robustness and convergence in the one-stage fitting approach have been noted. These include:

- Data for the USA (Cairns et al. (2009) and Currie (2016))
- Data for Netherlands (van Berkum et al., forthcoming)
- Data for Spain (Debón et al. (2010))

The results with inclusion of the additional constraint for these datasets, as well as for the England and Wales Males and Females are summarized in the following table 4.

Dataset				Log-likelihood		
Country	Gender	Age	Model M		Model H1	
		Range	Without	With	Without	With
			$\operatorname{constraint}$	constraint	$\operatorname{constraint}$	$\operatorname{constraint}$
E-W	Male	0-89	-21,992	-22,400	-22,400	-22,407
E-W	Male	60-89	-8,847	-8,847	-8,999	-9,003
E-W	Female	0-89	-20,449	-20,197	-20,797	-20,799
E-W	Female	60-89	-8,448	-8,448	-8,642	-8,649
USA	Male	0-89	-38,096	-39,510	-41,467	-43,709
USA	Male	0-89	$28,\!691$	29,085	-30,323	-30,489
NL	Female	0-89	-17,514	-17,522	$-17,\!698$	-17,721
Spain	Male	0-89	-23,370	-23,410	$-25,\!517$	-26,530

Table 4: Poisson log-likelihood for Models M and H1 in the one-stage approach with and without the approximate identifiability constraint

In Hunt and Villegas (2015) the authors note the other data-sets show many of the same issues with robustness and stability as those in the data for England and Wales Males in models M and H1. The use of the additional constraint partially resolves these issues, especially when using the H1 model. Thus these results are, therefore, strongly indicative that the issues and solutions are general features of models M and H1 and are not just specific to a single data set. However, it should also be noted that the difference in fit due to the additional constraint in the USA data is more significant, indicating that the values of the fitted κ_t are less linear compared to the other models. As such, one should handle this with care.

10 Replicating the Tests

As described in Currie (2016), one can use the GNM (Generalized Nonlinear Models) R-package to fit the data. The GNM package is more detailed described in Turner and Firth (2007). This is utilized in the R-package StMoMo (stochastic mortality models) as described in Villegas et al. (2015). In order to effectively use StMoMo with the approximate additional constraint as described earlier, one has to make certain adjustments in a few functions of both the StMoMo and the GNM package, as StMoMo uses GNM implicitly. Using this I made an attempt to replicate the results. As such, I tried to stay as close to the original code as possible, only adding the constraint and altering the code on places that disallowed the use of approximate transformations to the original fit-ted values. Yet, I obtained slightly different results compared to Hunt and Villegas (2015).

I tried to fit models M, H1 and APC to the data for three slightly different data-sets²:

- England and Wales Male data, age 0-89, years 1961-2007
- England and Wales Male data, age 0-89, years 1971-2007
- England and Wales Male data, age 0-89, years 1981-2007

 $^{^{2}}$ More detailed information is available from the author.

10.1Model M

Without the additional constraint, the dataset for years 1971-2007 fails completely³. By adding the constraint, the set behaves better, but is still way of the other parameter values. Even more interesting, the values of the κ_t , which are used for times series forecasting in Lee and Carter (1992) show different slopes both with and without a constraint, as such, it seems to be meaningless to use them. In general, model M seems to be lacking robustness to be of any use, whatsoever.

10.2Model H1

Model H1 seems to show more robustness, with regard to the fitting procedure, but it also obtains different values for the parameters. As such, it is not robust with respect to the parameters, however, it seems to be more robust compared to model M.

10.3Convergence

By subsetting the data based on the age in subsets for age 0-i, $\forall i \in [10, 89]$, one can assess roughly the time that would be saved by using the additional constraint. Whereas Hunt and Villegas (2015) finds performance increase, my findings are more modest, table 5.

	Table 5. Overview midnigs by etapsed time, convergence and failures						
Model	Elapsed time without constrain (min) t	Elapsed time with constraint (min)					
М	95.11	89.65					
H1	60.85	73.56					
Model	Convergence without constraint $(\%)$	Convergence with constraint $(\%)$					
М	40.65	45.05					
H1	71.25	73.75					
Model	Failures without constraint $(\%)$	Failures with constraint $(\%)$					
М	24.18	25.28					
H1	0	0					

Table 5: Overview findings by elapsed time, convergence and failures

So, although the constraint seems to speed up model M slightly and solves the convergence problem partially, it does so for a price: e.g. the chance of a failure is higher, which makes sense as one uses an approximate transformation. Unwanted conditions during the iterative optimization could potentially be very harmful and lead to unexpected outcomes in terms of parameters. For model H1, it should be clear that the extra costs in time do not weigh against the slight benefit in terms of convergence.

All in all, I have to conclude from my results that the usage of the additional constraint is not beneficial to fitting the model. Even more so, it seems that the usage of model M and model H1, in terms of this data-set, should be avoided.

³More detailed information is available from the author.

11 Conclusions

Compared to the conclusions drawn in the previous section, the authors of Hunt and Villegas (2015) draw different conclusions. They agree that the one-stage fitting procedure has considerable covergence and robustness problems, making the model sensitive to both the details of the fitting algorithm, the convergence criteria and the data the model is fitted to. They also find that model H1 is both more robust and achieves convergence more quickly. Also it is concluded that the addition of the extra constrain solves some of the robustness issues, but does not still not stabilize the model. A reason might be the fact that it is difficult to allocate structure in the data and assess the interactions between the variables. In conclusion, they argue for the use of model H1 in combination with the additional constraint, based on theoretical justification and improved fit to data of the one stage-procedure, as has been argued in Cairns et al. (2009). This also improves the robustness of the model with respect to changes in the underlying data.

As such, I arrive at different conclusions, while using the same data and R-package, assuming Hunt and Villegas (2015) use StMoMo and GNM as well. The results I have obtained compel me to conclude that both model M and model H1 have serious disadvantages with respect to robustness and convergence. To obtain credible forecasts, neither model M nor H1 are supposedly to be used.

However, as stated in Beutner et al. (2016) the problem might be in the number of constraints and the number of parameters. For example, in the appendix⁴, one can find a section with graphs for the APC-model. These graphs show more robustness, while the model only contains three parameters and no multiplicative elements. Therefore, for modeling cohort effects this would be more suitable. For modeling with H1 or M, one should perhaps consider thus more constraints and even different constraints because the two constraints considering ι :

$$\sum_{i=0}^{i=1} \iota_y = 0$$
$$\sum_{i=0}^{i=1} (y - \bar{y})\iota_y = 0$$

in combination with the result that κ_t tends to be linear, might be problematic. As the other elements in the model α_x , $\beta_x^{(0)}$ and $\beta_x^{(1)}$ are fixed over time, changes of mortality rates over time are explained by ι_y and κ_t . Then imposing the above restriction on ι_y causes ι_y to be either random around the $\iota = 0$ -line or causes all ι_y to be zero. If you apply the algorithm described in Hunt and Villegas (2015), you find that this particular combination of constraints may cause the loglikelihood value to become negative infinity and thus failing in general. Empirically, this is thus problematic.

The exact underlying mechanism is complex and more research should be focused on the underlying dynamics due to the constraints. Also, more attention should be paid to the nature of the data. Quite frankly, it is unwanted to assume certain model- and constraintstructures without a thorough analysis of the analytical goals and the underlying data.

⁴Available upon request

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